## Xinran Tang

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## Education

University of Central Florida	Orlando, FL	
PhD in Computer Engineering, Advisor: George Atia	Aug. 2024 - Present	
New York University	New York, NY	
MS in Computer Engineering, Advisor: Chen Feng, Cumulative GPA: 3.77/4.0	$Sept. \ 2022 - May. \ 2024$	
University of Nottingham	UK	
BSc Honours in Computer Science, First Class Degree	$Sept. \ 2018 - Jun. \ 2022$	

## TECHNICAL SKILL

**Programming languages**: Python, Java, C/C++, MATLAB, LaTeX, VHDL/Verilog, HTML/CSS/JavaScript, Git **Frameworks/Libraries**: PyTorch, OpenCV, OpenAI.Gym, CUDA programming , OpenGL, ROS/ROS 2, HPC Toolkit, React

**OS**: Linux, MacOS, Windows

## **Research Projects**

Robust Robust Reinforcement Learning from Human Feedback	Aug. 20	24 – Present
University of Central Florida, Prof. George Atia		
• Implement robust RLHF with uncertainty in reward distributions		
Visual Room Rearrangement	Oct. 2023	– May. 2024
New York University, AI4CE Lab		
<ul><li>Used YOLO and Segment Anything Model (SAM) to segment objects in the AI2The</li><li>Integrated scene reasoning via Large Language Model (LLM).</li></ul>	or simulator.	
Embodied AI Platform	Sep. 2023	– May. 2024
New York University, AI4CE Lab, NYU self-drive VIP Student Team Leader		
<ul> <li>Implement visual navigation task using simulation platform with limited GPU resour</li> <li>Further capture the real-world images using TurtleBot (Raspberry Pi + Raspberry F</li> <li>Implement the algorithm into the real world platform.</li> </ul>		good result.
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Reinforcement Learning for Robot Grasping New York University, MMVC Lab	Mar. 2023	– Jun. 2024
<ul> <li>New Fork University, MMVC Lab</li> <li>Automatically designed best encoder models using LLM for different robot environm</li> </ul>	onts	
• Integrated an evolutionary algorithm to drive the NAS algorithm.		
• Conducted training sessions in OpenAI Gym environments, including Hopper, Huma self-designed environments, including push box and slide puck.	noid, and Swim	mer; MuJoCo
<b>3-D Multi-Camera Gaze Estimation System with Long Distance</b> University of Nottingham, Prof. Ying Weng	Jun. 2020	– Jun. 2022
<ul> <li>Achieved consistent gaze detection for head rotations between -60° and 60° across lor</li> </ul>	ng distances	
• Optimized gaze estimation through vector dynamics between pupil center and corner	0	
• Transitioned from 2D to an innovative 3D model using a cutting-edge deflection mat		
• Enhanced accuracy by uniquely weighting side cameras and combining data from the cameras.	ee FLIR Blackf	y S USB3
wards & Honors		
CF Graduate Artificial Intelligence Initiative Fellowship		2024 - 2025
YU Graduate School of Engineering Scholarship		2022 - 2024
The Appreciate Presenter at the 2021 4th International Conference on Computing an	nd BigData	Nov. 2021
The Meritorious Winner of 2021 Interdisciplinary Contest in Modeling		Feb. 2021
The Successful Participant Award of Asia and Pacific Mathematical Contest in Mode	eling	Nov. 2020

The Second prize of the 10th National MathorCup university mathematical modeling challenge

Jun. 2020